Combining HTM and RCU to Implement Highly Efficient Balanced Binary Search Trees

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Outline

- Binary Search Trees (BSTs)
- Concurrent BSTs
- RCU-HTM
- Experimental results
- Conclusions & Future work



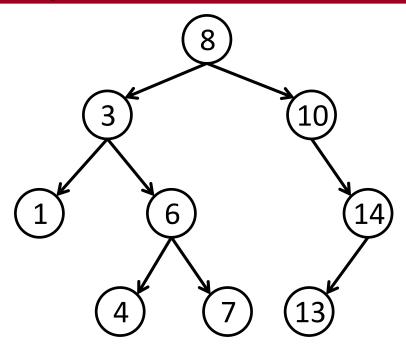


BINARY SEARCH TREES





Binary Search Trees (BSTs)

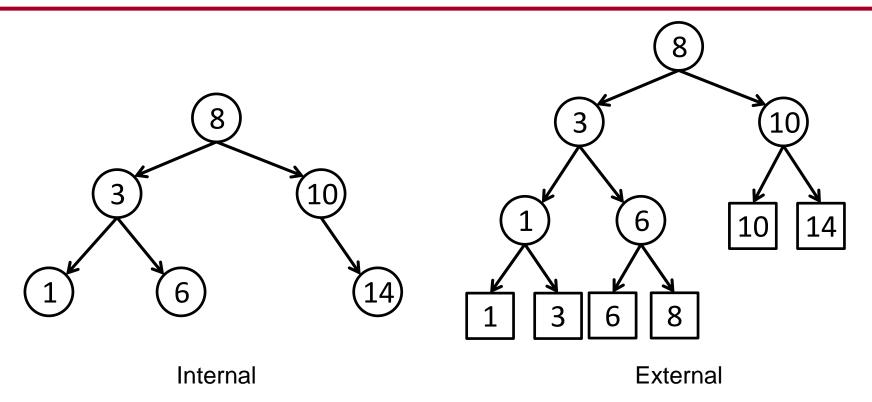


- A classic binary tree with an additional property:
 - Nodes in left subtree have keys less than the key of the root, nodes in right subtree have keys greater than the root.
- Most commonly used to implement dictionaries:
 - <key,value> pairs
 - 3 operations: lookup(key), insert(key, value) delete(key)





Internal vs. External BSTs



Internal: <key,value> pairs in every node

External: values only in leaves, internal nodes only contain keys.

- External trees simplify the delete() operation
- They require twice as much memory
- Longer traversal paths







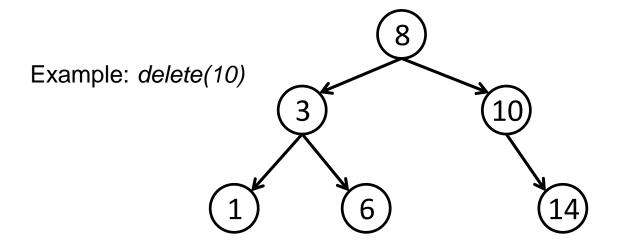


- Deleting a node with one or zero children is easy
 - Just change parent's child pointer





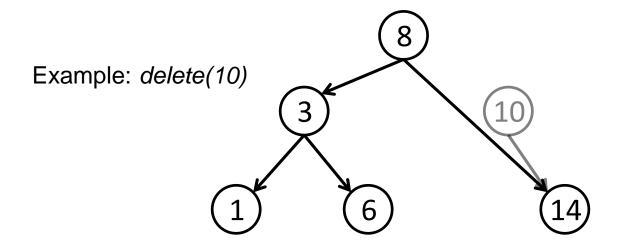
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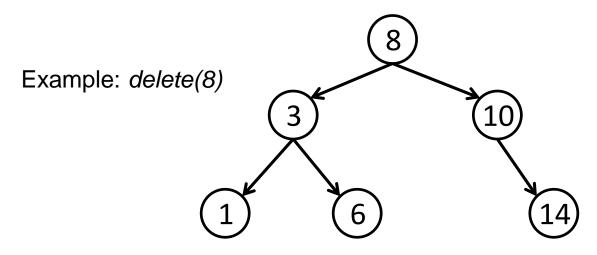


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- Deleting a node with two children is more complicated
 - Need to find successor, swap keys and remove successor node
 - Successor may be many links away





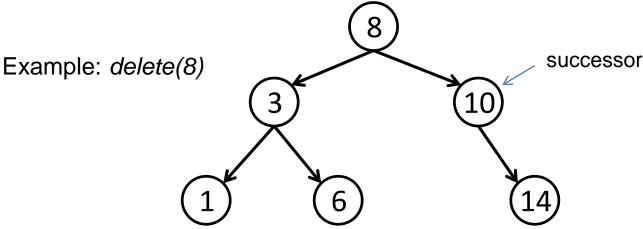
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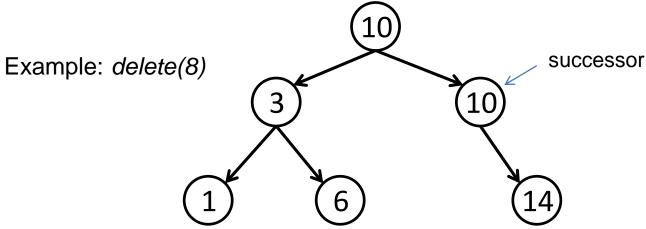
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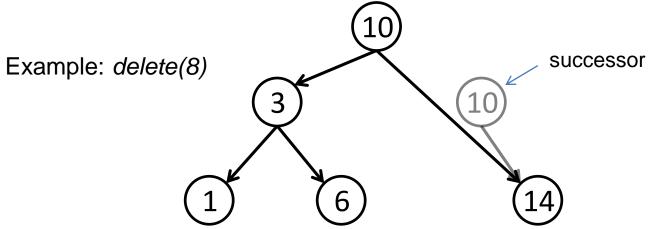






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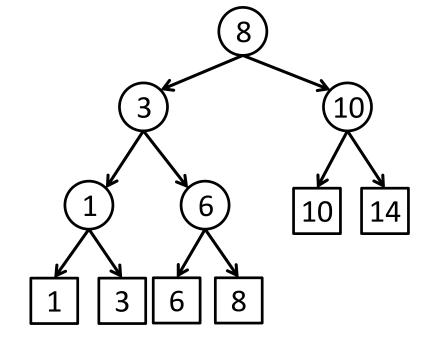
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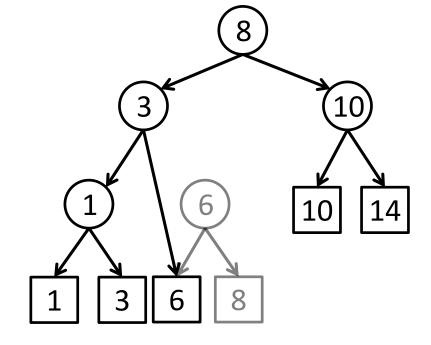
Example: delete(8)



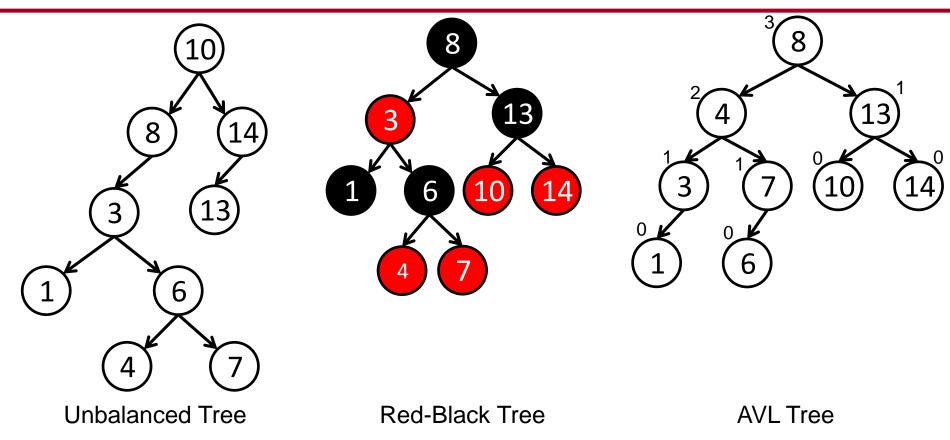


Deletion is always simple

Example: delete(8)



Unbalanced vs. Balanced BSTs



- + Balanced trees limit the height of the tree (i.e., the length of maximum path) to provide bounded and predictable traversal times
- Rebalancing requires additional effort after insertions/deletions





```
int bst_insert(bst_t *bst, int key, void *value)
{
   traverse_bst(bst, key);
   if (key was found) return 0;
   insert_node(bst, key, value);
   return 1;
}
```



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int bst insert(bst t *bst, int key, void *value)
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  insert node (bst, key, value);
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                            Example:
                                                  8
                            bst insert(key = 2)
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}
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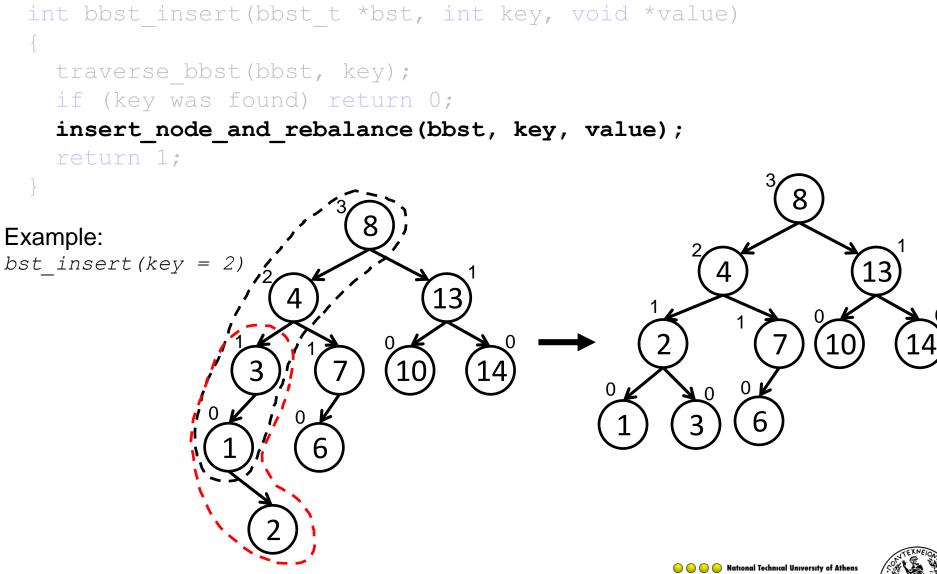
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CONCURRENT BINARY SEARCH TREES





Concurrent BSTs

There are 2 challenges for concurrent <u>internal</u> and <u>balanced</u> BSTs:

- 1. The deletion of a node with 2 children requires exclusive access to the whole path from the node to the successor.
- 2. Rebalancing requires several modifications that need to be performed in a single atomic step.

Proposed non-blocking and lock-based concurrent BSTs are either:

- Unbalanced [Natarajan PPoPP'14, Howley SPAA'12, Ellen PODC'10]
- Relaxed balanced [Bronson PPoPP'10, Drachsler PPoPP'14, Brown PPoPP'14]
- External [Natarajan PPoPP'14, Ellen PODC'10]
- Partially external [Bronson PPoPP'10]



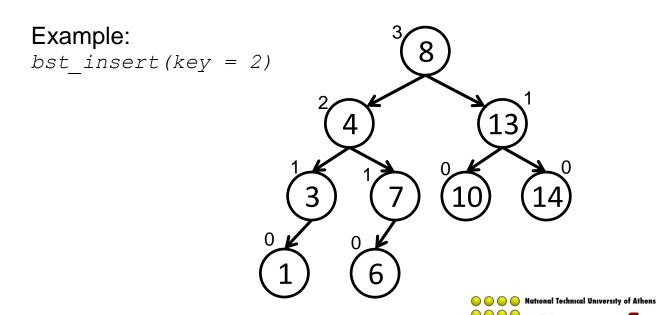


- Read-Copy-Update (RCU)
 - Modifications are performed in copies and not in place. Copies are atomically installed in the shared data structure.
 - Readers may proceed without any synchronization and without restarting
 - Updaters need to be explicitly synchronized (most commonly only a single updater is allowed to operate)





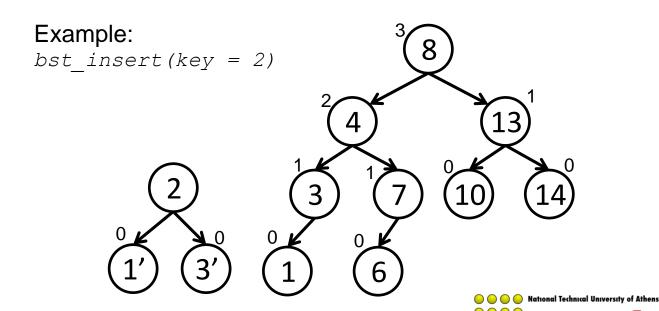
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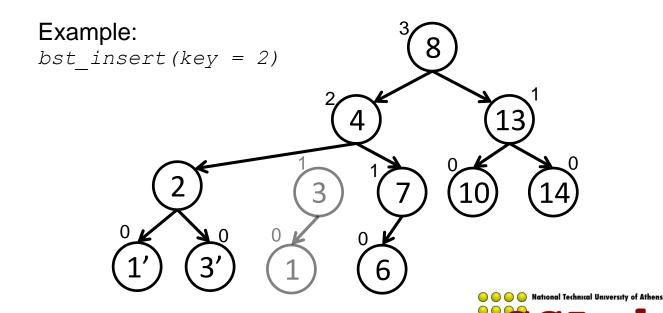


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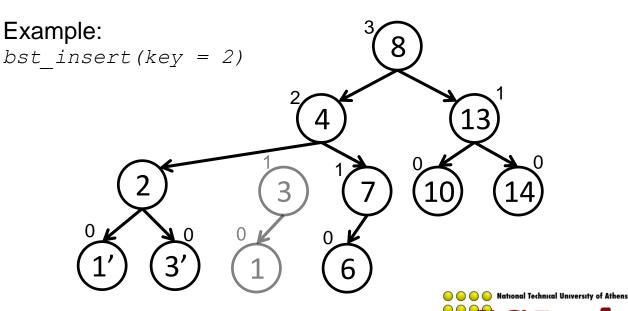
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Old readers may still traverse old versions of nodes. New readers will see the new nodes.

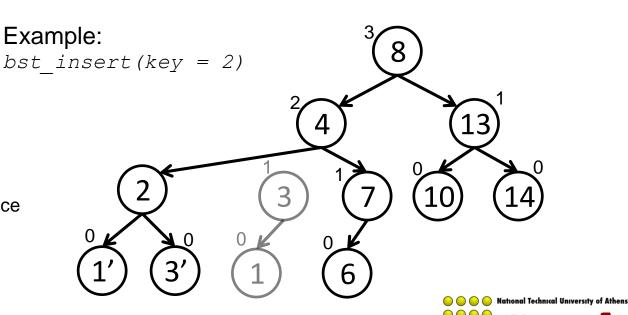




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- Read-Copy-Update (RCU)
 - Modifications are performed in copies and not in place. Copies are atomically installed in the shared data structure.
 - Readers may proceed without any synchronization and without restart Single updater RCU tree:
 - Updat single
- Multiple readers
 - Single updater

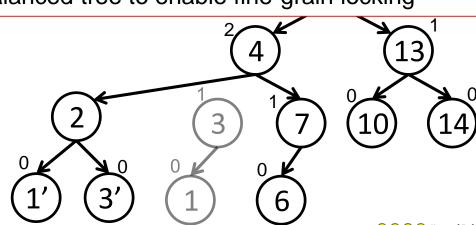
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Citrus RCU tree [Arbel PODC'14]:

- Multiple updaters using fine-grain locks.
- Unbalanced tree to enable fine-grain locking

Old readers may still traverse old versions of nodes. New readers will see the new nodes.

Updaters can safely replace parts of the tree as only a single updater is allowed.







Concurrent HTM-based BSTs

- Hardware Transactional Memory (HTM)
 - Avoids STM's huge overheads
 - Allows the modification of multiple locations atomically \rightarrow good fit for the rebalancing phase in a BBST
- HTM-based BSTs:
 - Coarse-grained HTM (cg-htm):
 - Each operation enclosed in a single transaction
 - + Easy to implement
 - Large transactions (increased conflict probability)
 - Consistency-Oblivious-Programming HTM (cop-htm) [Avni TRANSACT'14]:
 - The traversal is performed outside the transaction
 - The executed transaction includes 2 steps:
 - Validate that the traversal ended at the correct node
 - Insert/Delete the node and rebalance if necessary
 - + Shorter transactions than cg-htm
 - Traversals (and consequently lookup operations) may need to restart

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RCU-HTM

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RCU-HTM

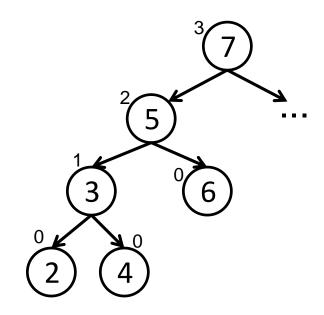
Combines **RCU** with **HTM** in an innovative way and provides trees with:

- 1. Asynchronized traversals (thanks to RCU)
 - Oblivious of concurrent updates in the tree
 - No locks, no transactions or any other synchronization
 - No restarts
- 2. Concurrent updaters (thanks to HTM)
 - All updates are performed in copies
 - Modified copies are first validated and then installed in the tree
 - An HTM transaction is used for the validation+installation phase
 - HTM transaction includes several reads but only a single write \rightarrow minimized conflict probability





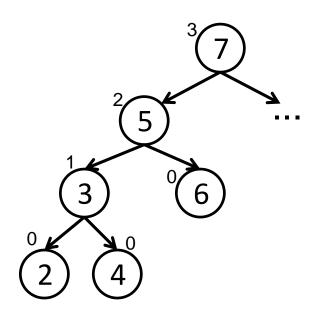
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- 1. Traverse the tree to locate the insertion point
 - During traversal we maintain a stack of pointers to the traversed nodes



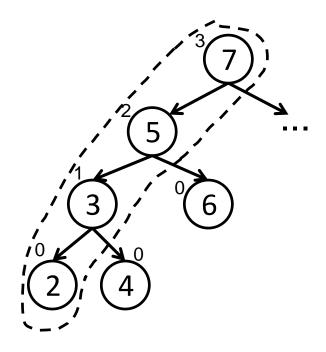




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Example: *insert(key = 1)*

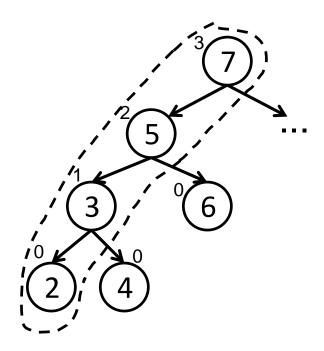
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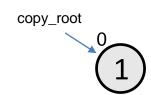
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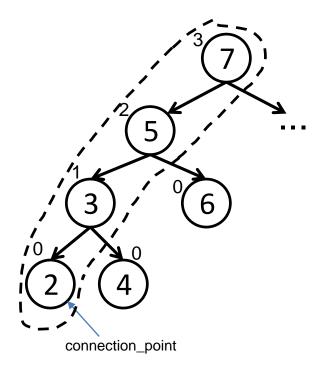






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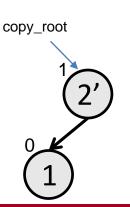


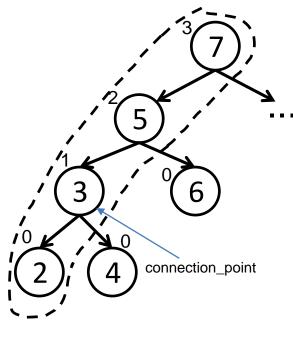






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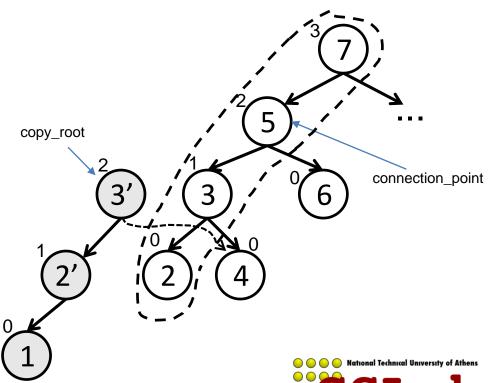




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Example: insert(key = 1)

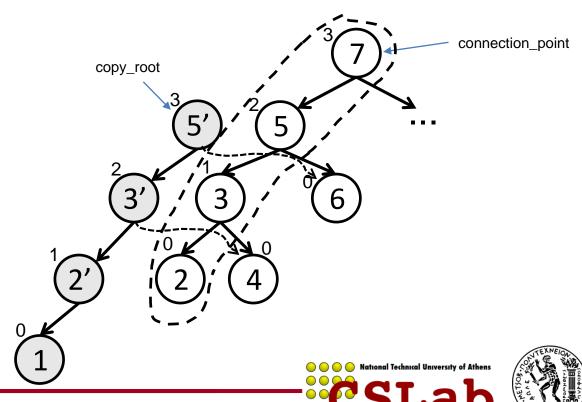
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connection point

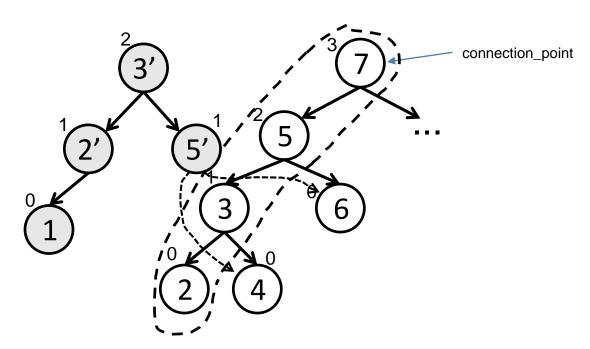
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- 3. Validate the modified copy
 - For each copied node check that children pointers haven't been modified since we copied the node
 - Also validate the access path followed during traversal

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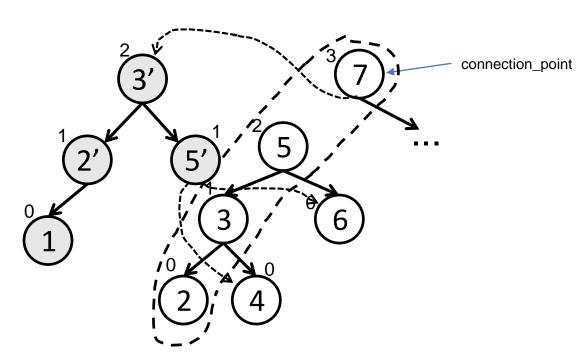
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 - Change connection_point's child







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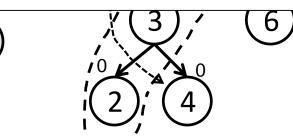


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Steps 3 and 4 performed atomically inside an HTM transaction

If the validation in step 3 fails we abort the transaction and restart the operation

For the non-transactional fallback path we use a lock that allows only a single updater.

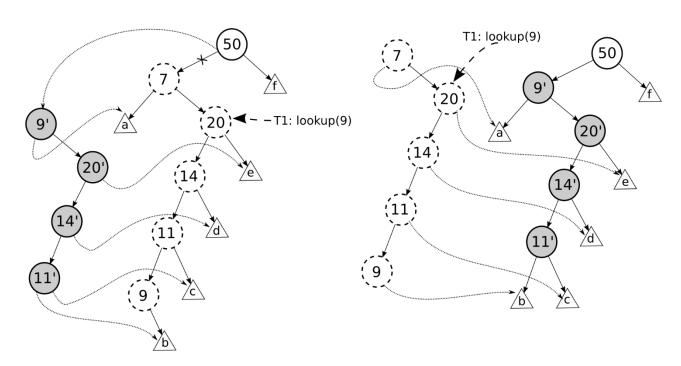






RCU-HTM: delete operation

- Similar to insert
- One difference:
 - When we delete a node with two children we need to copy the whole path to its successor







EXPERIMENTAL RESULTS





Experimental Setup

- Intel Broadwell-EP Xeon E5-2699 v4
 - 22 cores / 44 hyperthreads @ 2.2GHz
 - 64 GB of RAM
- GCC 4.9.2, -O3 optimizations enabled
- Scalable memory allocator (jemalloc)
- No memory reclamation
- All threads pinned to hardware threads (hyperthreads enabled only at 44-threaded executions)
- **Experiments:**

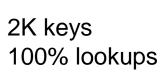
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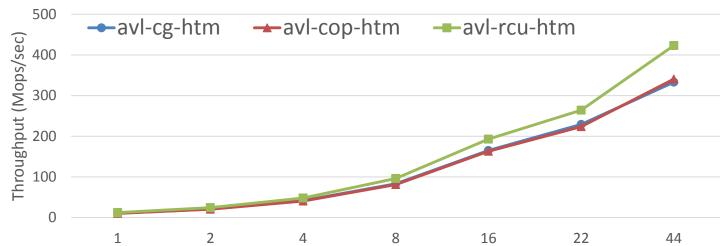
- Threads run for 2 seconds, executing randomly chosen operations (lookups/inserts/deletes)
- 3 Workloads: 100%, 80% and 20% lookups, and the rest equally divide between insertions and deletions

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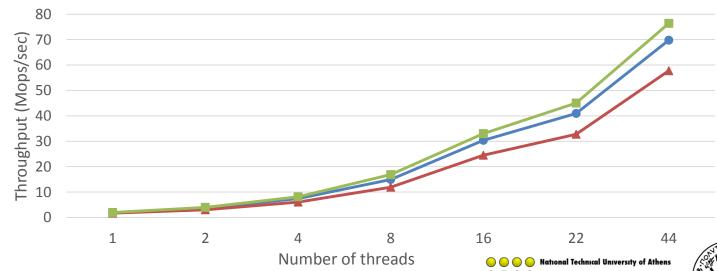
3 tree sizes: 2K keys, 20K keys and 2M keys

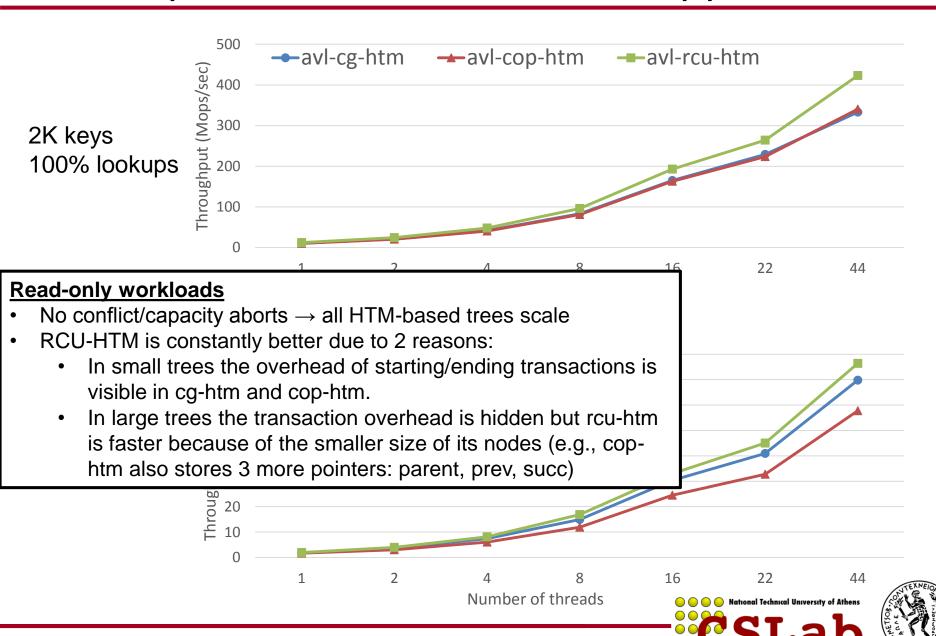




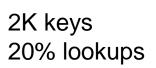


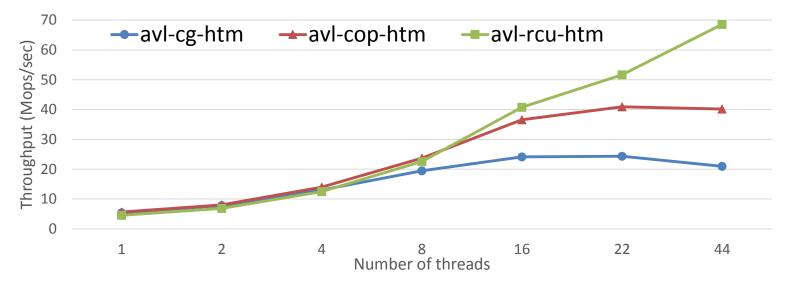
2M keys 100% lookups



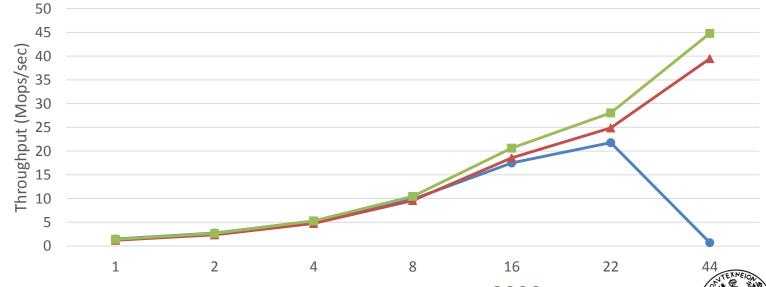


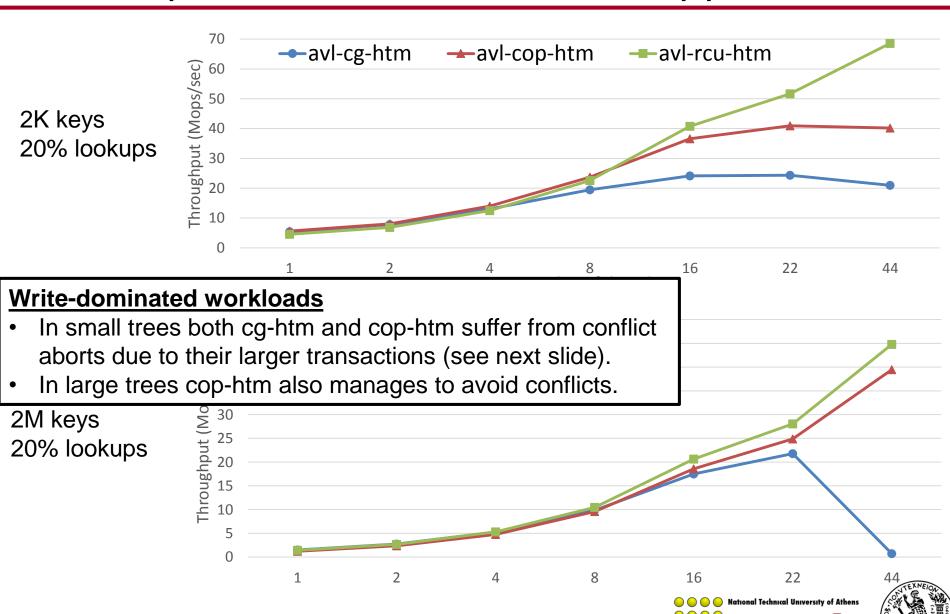
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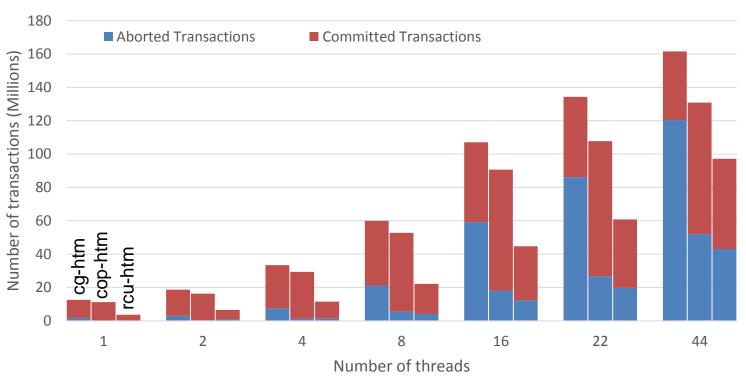


2M keys 20% lookups





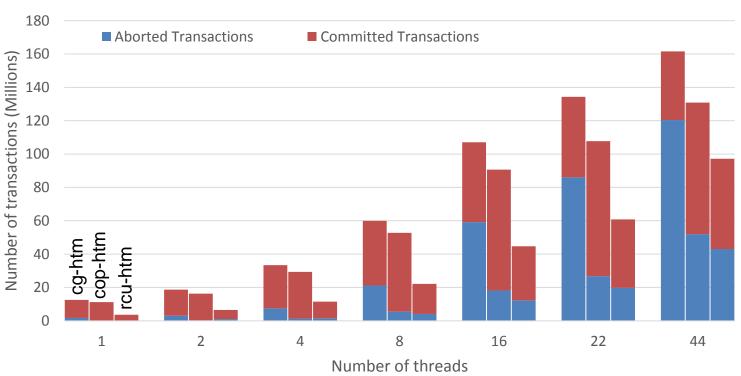
2K keys – 20% lookups









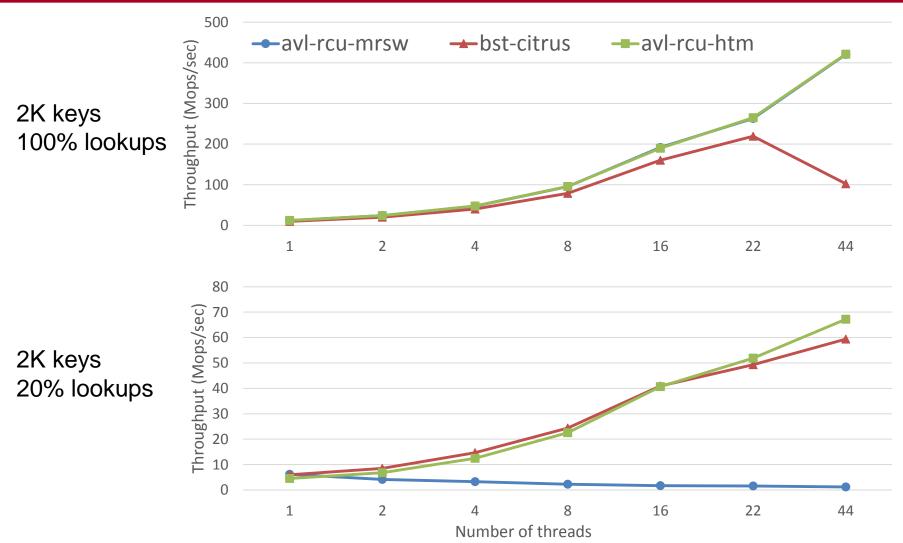


RCU-HTM executes much less transactions and suffers less aborts.





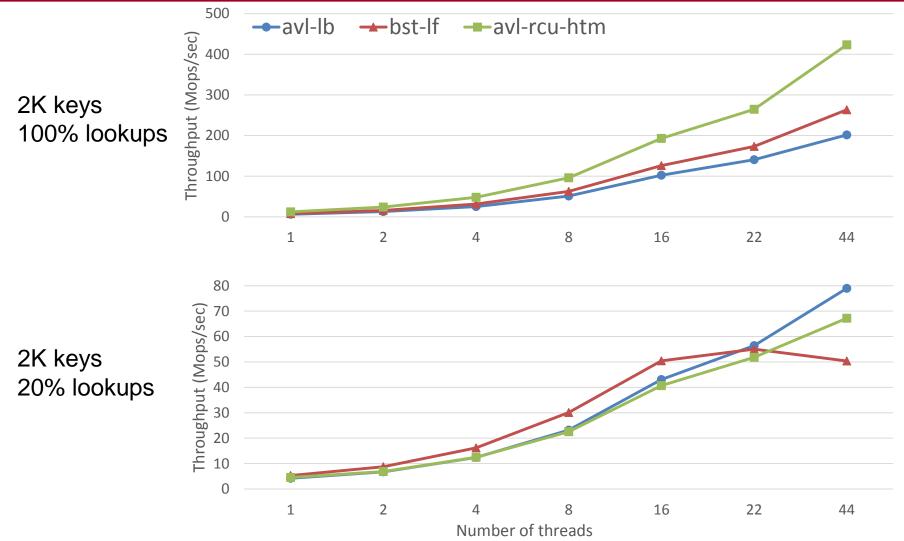
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avl-rcu-mrsw: writers synchronized using a single lock bst-citrus: unbalanced BST, RCU for readers, fine-grain locks for writers [Arbel PODC'14]



Comparison with state-of-the-art

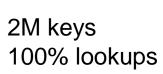


avl-lb: relaxed balance lock-based AVL tree [Bronson PPOPP'10] bst-lf: unbalanced lock-free (CAS-based) tree [Natarajan PPoPP'14]



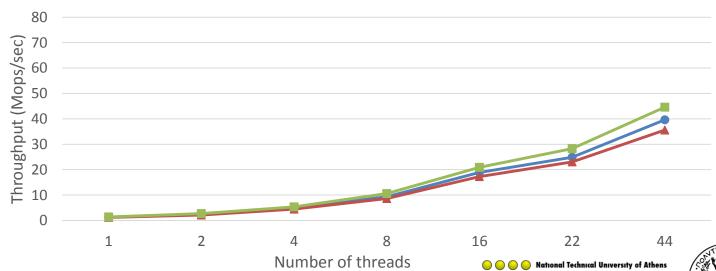


Comparison with state-of-the-art





2M keys 20% lookups



CONCLUSIONS & FUTURE WORK





Conclusions & Future Work

- RCU-HTM combines RCU with HTM and provides concurrent BSTs that are:
 - Internal
 - Strictly balanced
 - Efficient both for readers and updaters

- Future work
 - Memory reclamation
 - Formal proof of correctness (linearizability)
 - More BSTs (e.g., B+-trees, Splay trees, etc.)

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THANK YOU! QUESTIONS?

ACKNOWLEDGMENT

Intel Corporation for kindly providing the Broadwell-EP server on which we executed our experiments.



